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Signed M Cooke

Dated 17 December 2001
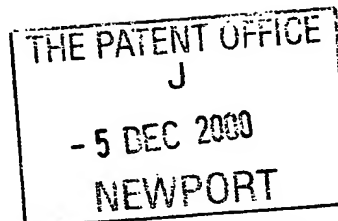
Patents Form 1/77

Patents Act 1977
(Rule 16)

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South Wales
NP9 1RH

050EC00 E588850-1 D01063
P01/7700 0200-0029564?2

1.	Your reference	JSR.P51357GB	
2.	Patent application number *(The Patent Office will fill in this part)*	**0029564.2**	**E5 DEC 2000**

3. Full name, address and postcode of the or of each applicant *(underline all surnames)*

Mitel Semiconductor Limited
Cheney Manor
Swindon
Wiltshire SN2 2QW

Patents ADP number *(if you know it)*

If the applicant is a corporate body, give the country/state of its incorporation

United Kingdom

7387442001

4. Title of the invention

Radio Frequency Tuner

5. Name of your agent *(if you have one)*

"Address for service" in the United Kingdom to which all correspondence should be sent *(including the postcode)*

Marks & Clerk
4220 Nash Court
Oxford Business Park South
Oxford
OX4 2RU

7271125001

Patents ADP number *(if you know it)*

		Country	Priority application number *(if you know it)*	Date of filing *(day / month / year)*
6.	If you are declaring priority from one or more earlier patent applications, give the country and the date of filing of the or of each of these earlier applications and *(if you know it)* the or each application number			

		Number of earlier application		Date of filing *(day / month / year)*
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8. Is a statement of inventorship and of right to grant of a patent required in support of this request? *(Answer 'Yes' if:*
   a) *any applicant named in part 3 is not an inventor, or*
   b) *there is an inventor who is not named as an applicant, or*
   c) *any named applicant is a corporate body.*
   See note (d))

Yes

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Continuation sheets of this form	None
Description	1
Claim *(s)*	3
Abstract	1
Drawing *(s)*	4

10. If you are also filing any of the following, state how many against each item.

Priority documents	No
Translations of priority documents	No
Statement of inventorship and right to grant of a patent *(Patents Form 7/77)*	I
Request for preliminary examination and search *(Patents Form 9/77)*	I
Request for substantive examination *(Patents Form 10/77)*	No
Any other documents *(please specify)*	No

11. I/We request the grant of a patent on the basis of this application.

Signature *Marks & Clerk*   Date 4-12-06

12. Name and daytime telephone number of person to contact in the United Kingdom

John S. Robinson - 01865 397900

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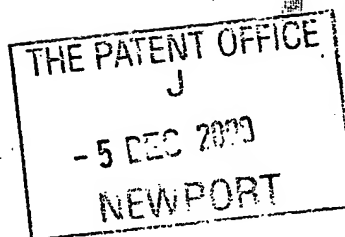
Statement f inventorship and f right to grant of a patent

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1.	Your reference	JSR.P51357GB	
2.	Patent application number *(if you know it)*	**0029564.2**	⊢5 DEC 2000
3.	Full name of the or of each applicant	Mitel Semiconductor Limited	
4.	Title of the invention	Radio Frequency Tuner	
5.	State how the applicant *(s)* derived the right from the inventor *(s)* to be granted a patent	By virtue of employment	
6.	How many, if any, additional Patents Forms 7/77 are attached to this form? *(see note (c))*	None	

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I/We believe that the person *(s)* named over the page *(and on any extra copies of this form)* is/are the inventor *(s)* of the invention which the above patent application relates to.

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Date
4·12·00

8. Name and daytime telephone number of person to contact in the United Kingdom

John S. Robinson – 01865 397900

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Enter the full names, addresses and postcodes of the inventors in the boxes and underline the surnames

Nicholas Paul COWLEY
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SN4 0RT

Patents ADP number *(if you know it):* 1017722003

Patents ADP number *(if you know it):*

Reminder

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Patents ADP number *(if you know it):*

Radio Frequency Tuner

The present invention relates to a radio frequency tuner. Such a tuner may be used as a cable tuner for receiving modulated digital signals from a cable distribution network, for example, as a set top box for receiving television signals. Other applications include use for cable telephony and as a modem for data signals.

Known types of cable tuners may be of the single conversion or double conversion type. By way of illustration, Figure 1 of the accompanying drawings illustrates a double conversion cable tuner for digital signals. The tuner has an input 1 for connection to a cable distribution network and connected to an automatic gain control (AGC) stage 2. The output of the stage 2 is connected to a first frequency changer 3 for performing up-conversion and comprising a mixer 4 and a local oscillator 5 controlled by a phase locked loop (PLL) synthesiser 6.

The output of the first frequency changer 3 is connected via a first intermediate frequency filter 7 to a second frequency changer 8 of the down-conversion type. The second frequency changer 8 comprises a mixer 9 and a local oscillator 10 controlled by a PLL synthesiser 11. The output of the second frequency changer 8 is supplied by a second intermediate frequency filter 12 to an intermediate frequency (IF) amplifier 13 whose output supplies an IF signal to the output 14 of the tuner.

Figure 2 of the accompanying drawings illustrates a typical cable distribution system. The system comprises an optical fibre "backbone" 20 which supplies a plurality of head end distribution units 21. Each of the units 21 services a plurality of properties, such as houses and offices, as illustrated at 22. A cable 23 connects each property to its head end unit 21, which supplies the signals from the distribution network and which also supplies power to a modem 24 including a tuner of the type shown in Figure 1. The modem 24 is continuously powered and supplies a telephony service by means of a conventional twisted pair 25 and a cable service for further modem applications such as television and internet as illustrated at 26.

The tuner is required to convert any selected channel from the cable distribution network to an intermediate frequency in the form of a signal having characteristics which are sufficient to ensure acceptable perceived performance. For example, the signal to noise plus intermodulation performance must be sufficient for acceptable television or data signals to be provided. The signals from the cable distribution network are supplied to the AGC stage 2 which controls the signal level supplied to the first frequency changer 3 so as to provide an acceptable intermodulation performance of the first frequency-changer. In general, little or no filtering takes place before the frequency changer 3, which is therefore required to have a high level of performance.

The frequency changer 3 performs block up-conversion of the broad band input signal with the frequency of the local oscillator 5 being selected by the synthesiser 6 such that a desired channel is centred on a high first intermediate frequency. The synthesiser 6 and the synthesiser 11 are, for example, controlled via an I2C bus micro-controller (not shown).

The output of the first frequency changer 3 is filtered by the filter 7, which has a centre frequency at the predetermined first intermediate frequency and a pass-band characteristic such that the desired channel and a small number of further channels on either side of the desired channel are supplied to the second frequency changer 8.

The second frequency changer 8 performs a block down-conversion such that the desired channel is centred on the second much lower intermediate frequency. The output signal of the second frequency changer 8 is filtered by the filter 12 whose centre frequency is centred on the centre frequency of the desired channel following the second conversion and which has a pass-band for passing the desired channel and for rejecting or substantially attenuating the adjacent channels. The desired channel at the second intermediate frequency is amplified by the amplifier 13 and supplied to the tuner output 14.

Known types of tuner (of the type shown in Figure 1 and of other types such as the single conversion type) are required to be able to cope with all extremes of signal

conditions. In particular, such tuners are required to handle a wide dynamic range of signals and to cope with worst case composite signal loading, maximum channel to channel ripple and various other conditions, both singly and in any combination.

As a result of these requirements, for much of the time during operation, each tuner in a cable distribution system provides a much higher performance than is actually required by the individual channels being received. For example, in the case of modulated digital signals, there is no advantage in providing a tuner performance which exceeds a threshold value for signal to noise plus intermodulation performance. In such cases, the presence of complex Forward Error Correction techniques, such as Read Solomon Coding and Viterbi puncturing, means that there is no perceivable improvement in reception when a minimum threshold of signal to noise plus intermodulation is achieved.

The power consumption of a tuner is generally a direct function of the performance of the tuner. The term "direct function" in this context means that, for over at least a range of power consumptions, the performance of the tuner is a monotonic function of the power consumption of the tuner. Thus, more power is consumed, for example from the cable distribution network powering the modems 24, than is necessary to achieve the desired performance. Unnecessary power consumption is undesirable for many reasons, such as cost and environmental factors. With the increasing use of cable distribution systems and consequently of modems incorporating such tuners, the problem of increased power consumption is in turn increasing and is undesirable.

According to the invention, there is provided a radio frequency tuner comprising at least one stage whose performance is a direct function of power consumption thereof, a comparator for comparing the tuner performance with a first predetermined performance, and a power consumption control circuit for reducing the power consumption of the at least one stage when the tuner performance exceeds the first predetermined performance.

The comparator may be arranged to compare the tuner performance with a second predetermined performance lower than the first predetermined performance and the control circuit may be arranged to increase the power consumption of the at least one stage when the tuner performance is less than the second predetermined performance.

The tuner performance may be the ratio of signal to noise plus intermodulation products.

The tuner may comprise a digital tuner. The tuner may comprise a demodulator and the tuner performance may be the bit error rate.

The first predetermined performance may be greater than an acceptable minimum performance. The second predetermined performance may be less than or equal to the acceptable minimum performance.

The bit error rate may be the instantaneous bit error rate, a time-averaged bit error rate, or a combination therof.

The comparator may be arranged to perform the comparison continuously. As an alternative, the comparator may be arranged to perform the comparison periodically. As another alternative, the comparator may be arranged to perform the comparison each time the tuner is powered up. As a further alternative, the comparator may be arranged to perform the comparison each time a change of tuned frequency is requested.

The at least one stage may comprise at least one frequency converter stage. The at least one frequency converter stage may comprise at least one mixer whose transconductance is dependent on power consumption. The at least one mixer may comprise at least one load whose value is adjustable to compensate for changes in the transconductance. The at least one frequency changer may comprise at least one low noise amplifier whose gain is dependent on power consumption. The at least one frequency converter stage may comprise at least one local oscillator whose output level is controlled by the control circuit.

The at least one stage may comprise at least one intermediate frequency amplifier. The at least one intermediate frequency amplifier may have a gain which is controllable by the control circuit.

The tuner may comprise a cable tuner.

It is thus possible to provide a tuner of reduced power consumption compared with known types of tuner. The tuner ensures that an acceptable performance is provided for the signal or channel currently being received while reducing or minimising the power consumption. Although such a tuner may be used for any application, such a tuner may be used with advantage in cable distribution systems of the type described hereinbefore. Where such tuners are powered by the cable distribution system, the power consumption of the system can be reduced or minimised to provide a substantially lower power consumption than the known type of system. This can be achieved without any perceptible degradation in the received signals.

The present invention will be further described, by way of example, with reference to the accompanying drawings, in which:

Figure 1 is a block circuit diagram of a known type of double conversion cable tuner;

Figure 2 is a block schematic diagram of a known type of cable distribution system;

Figure 3 is a block circuit diagram of a cable tuner constituting an embodiment of the invention; and

Figure 4 is a block circuit diagram showing in more detail one of the stages of the tuner shown in Figure 3.

Like reference numerals refer to like parts throughout the drawings.

The digital cable tuner shown in Figure 3 is of the double-conversion type and is similar to that illustrated in Figure 1 . Accordingly, only the aspects of construction and operation which differ from those described with reference to Figure 1 will be described in detail.

The output of the IF amplifier 13 is connected to a demodulator 30 for demodulating the selected received channel in accordance with the type of modulation which it uses. For example, the demodulator 30 may be arranged to demodulate quadrature amplitude modulated signals in order to extract the required digital data, for example for television reception.

The demodulator 30 comprises an analogue/digital converter (ADC) stage 31 which converts the incoming IF signal to a corresponding digital signal. A forward error correction (FEC) stage 32 performs error correction and the corrected signal is supplied to a demodulator stage 33 which supplies the output signal of the demodulator 30. The demodulator 30 also comprises a bit error rate (BER) estimator 34, which provides a signal representing the bit error rate. This rate may be the instantaneous rate, a time averaged value, or any appropriate indication of the bit error rate suitable for the subsequent processing as described hereinafter.

The tuner comprises a microcontroller 35 which is connected to various parts of the tuner by means of a I2C bus 36. The microcontroller 35 sends and receives data via the bus 36 and performs various control operations, for example including controlling the synthesisers 6 and 11 so as to ensure that a channel selected for reception is correctly tuned. The microcontroller 35 receives data from the demodulator 30 including the bit error rate value provided by the estimator 34. In addition to the synthesisers 6 and 11, the microcontroller 35 controls the power consumption of the frequency changers 3 and 8 and the IF amplifier 13 via the bus 36.

The frequency changes 3 and 8 are modified as compared with the corresponding frequency changers shown in Figure 1 as illustrated in Figure 4. Thus, each frequency changer has a radio frequency (RF) input connected to a mixer stage 40 comprising a

low noise amplifier (LNA) 41 and a mixer 4, 9. The local oscillator 5, 10 comprises a voltage controlled oscillator (VCO) whose output is connected to a signal splitter 42, which supplies the local oscillator signal to the mixer 4, 9 and to the frequency synthesiser 6, 11. The frequency changer comprises a bus interface 43 having an input 44 for connection to the bus 36 and output busses connected to the frequency synthesiser 6, 11, the mixer stage 40 and an IF amplifier 45 whose input is connected to the output of the mixer 4, 9 and whose output 46 constitutes the IF output of the frequency changer.

The frequency synthesiser 6, 11 is controlled in the conventional way via the bus interface 43 so that the VCO 5, 10 is tuned to the desired frequency for converting the selected channel to the desired output intermediate frequency. The mixer stage 40 has a control input connected to the interface 43 so as to control the power consumption of this stage. Thus, the microcontroller 35 can control the power consumption of the mixer stage 40 via the bus 36, the input 44, and the bus interface 43. The power consumption of the LNA 41 or of the mixer 4, 9 or of both of these may be controlled.

The performance of the mixer stage 40 depends on its power consumption. In particular, the transconductance gm and hence the gain is a direct function of the power consumption of this stage. Further, the intermodulation performance is a direct function of the power consumption. Thus, throughout at least a part of the range of power consumptions of this stage, as the power consumption is increased, the transconductance, gain and the intermodulation performance all increase or improve monotonically.

In order to compensate for variations in gain as a result of variations in transconductance resulting from varying the power consumption of the stage 40, the LNA 41 or the mixer 4, 9 or both may have a load whose value is varied simultaneously with varying the power consumption of the stage. Such an arrangement allows changes in gain resulting from changing the power consumption of this stage to be at least partly compensated. However, although it is possible to compensate for gain variations as a result of controlling the power consumption, other aspects of performance such as the

intermodulation performance are reduced as the power consumption of the stage is reduced.

The bus interface 43 is also connected to the IF amplifier or buffer 45 in order to control its power consumption. Again, as the power consumption of the buffer 45 is reduced, its transconductance and hence it gain is reduced. Again, the buffer 45 may have a programmable load impedance which is controlled so as to compensate at least partly for reduced transconductance with power consumption in order to restore at least partly the gain of this stage and make it less sensitive to changes in power consumption.

The interface 43 is also connected to the VCO 5, 10 so as to control the power consumption of the oscillator. As the power consumption is reduced, the phase noise performance of the oscillator 5 is reduced.

When the tuner shown in Figures 3 and 4 is initially powered and/or periodically thereafter, an adjustment routine is controlled by the microcontroller 35 in order to minimise the tuner power consumption while maintaining an acceptable minimum performance for reception of a selected desired channel. Initially, the power consumption of the tuner, particularly the frequency changers 3 and 8 and the IF amplifier 13, is set to a maximum value so that the tuner operates at its best performance level, for example in terms of signal to noise plus intermodulation performance. The microcontroller 35 controls the synthesisers 6 and 11 in accordance with a user request to select and receive a desired channel from the range of channels supplied to the tuner via the cable distribution network. The AGC stage 2, the frequency converters 3 and 8, the filers 7 and 12 and the amplifier 13 perform as described hereinbefore with reference to Figure 1.

The demodulator 30 digitises and error-corrects the IF signal, which is then demodulated to supply the channel signal, for example to a television receiver in the case of a channel providing a television service. The estimator 34 estimates the bit error rate and supplies this to the micro controller 35. The demodulator 30 also supplies to the microcontroller 35 data indicating the type of modulation scheme used by the

selected channel. For example, in the case of quadrature amplitude modulation (QAM), the demodulator indicates to the microcontroller 35 which QAM level is employed by the selected channel.

The microcontroller 35 determines on the basis of the type of modulation scheme and, in particular, the QAM level an acceptable performance for the selected channel. In the case of QAM, a high level modulation scheme such as QAM 256 requires a higher level of tuner performance that a lower level modulation scheme, such as QAM 16. The microcontroller 35 derives from the acceptable performance first and second predetermined performances which are higher and lower than the acceptable performance and compares the bit error rate from the estimator 34 with the first and second predetermined performances. If the bit error rate is such that the tuner performance exceeds the first pre-determined performance, the microcontroller 35 reduces the power consumption of the first frequency changer 3 by supplying the appropriate control signal as data via the bus 36, the input 44 and the bus interface 43 of the first frequency changer. In particular, the power consumption of the mixer stage 40 is reduced and this reduces the performance, particularly the signal to noise plus intermodulation performance, of the first frequency changer 4.

For as long as the bit error rate indicates a tuner performance in excess of the first pre-determined performance, the power consumption of the first frequency changer 3 is incrementally reduced and this process stops when the performance falls below the first predetermined performance. If the minimum power consumption of the first frequency converter 3 is reached before the performance falls below the first predetermined performance, then the power consumption of the second frequency changer 8 is incrementally reduced until it reaches a minimum permitted power consumption or its performance falls below the first determined performance. Thus, in this example, the full power consumption range of the first converter 3 is used before adjusting the power consumption of the second frequency converter. However, other control algorithms are possible and, for example, the microcontroller 35 may increment the power consumptions of the first and second frequency changers alternately. Also, the power

consumptions and hence performances of other stages, such as the oscillators 5 and 10, the buffers 45 and the amplifier 13 may be controlled using any appropriate strategy.

If the performance of the tuner as indicated by the bit error rate falls below the second predetermined performance, then the control algorithm is reversed and the power consumption is increased. In the previously described case where the full power consumption range of the first frequency changer 3 is used before adjusting the power consumption of the second frequency changer 8, the power consumption of the second frequency interchanger 8 is incremented upwardly to its maximum value and this is then repeated for the first frequency changer 3 until the performance exceeds the second predetermined performance. The gap between the first and second predetermined performances provides hysteresis to ensure stable operation of the control algorithm. Although the second predetermined performance has been indicated as being below the acceptable performance, it is also possible for the second predetermined performance to be equal to or greater than the acceptable performance but it should always be less than the first pre-determined performance.

This control algorithm may be performed on initially powering the tuner with the performance then remaining fixed until the tuner is depowered and repowered. As an alternative, the algorithm may be performed periodically whenever the tuner is powered. As a further alternative, this algorithm may be performed only when a different channel is selected by a user so as to ensure that the tuner power consumption is minimised for the selected channel while ensuring that the selected channel is received with acceptable performance.

The increments in power consumption of the or each controlled stage may be chosen so as to provide a desired overall performance of the tuner. For example, fixed increments may be used, in which case the degree of power consumption minimisation depends on the increment size, as does the rate at which the power consumption converges to a steady or more steady state. Alternatively, the increment sizes may be a function of the difference between the current tuner performance and the acceptable performance.

Such an arrangement provides a more rapid convergence but requires a slightly more complex control algorithm.

It is thus possible to minimise or at least reduce the power consumption of the tuner while maintaining acceptable performance for the received signals. In the case of digitally encoded signals, once an acceptable performance has been achieved, there is no need for a better tuner performance, which would require greater power consumption. The tuner may therefore be operated such that its power consumption is substantially less than would have to be provided by a known type of tuner without any perceivable degradation in the received signals.

CLAIMS:

1. A radio frequency tuner comprising at least one stage whose performance is a direct function of power consumption thereof, a comparator for comparing the tuner performance with a first predetermined performance, and a power consumption control circuit for reducing the power consumption of the at least one stage when the tuner performance exceeds the first predetermined performance.

2. A tuner as claimed in claim 1, in which the comparator is arranged to compare the tuner performance with a second predetermined performance lower than the first predetermined performance and the control circuit is arranged to increase the power consumption of the at least one stage when the tuner performance is less than the second predetermined performance.

3. A tuner as claimed in claim 1 or 2, in which the tuner performance is the ratio of signal to noise plus intermodulation products.

4. A tuner as claimed in any one of the preceding claims, comprising a digital tuner.

5. A tuner as claimed in claim 4, in which the tuner comprises a demodulator and the tuner performance is the bit error rate.

6. A tuner as claimed in any one of the preceding claims, in which the first predetermined performance is greater than or equal to an acceptable minimum performance.

7. A tuner as claimed in claim 6 when dependant on claim 2, in which the second predetermined performance is less than or equal to the acceptable minimum performance.

8. A tuner is claimed in claim 5 or in claim 6 or 7 when dependant on claim 5, in which the bit error rate is the instantaneous bit error rate.

9. A tuner as claimed in claim 5 or in claim 6 or 7 when dependant on claim 5, in which the bit error rate is a time-averaged bit error rate.

10. A tuner as claimed in Claim 5 or in claim 6 or 7 when dependent on claim 5, in which the bit error rate is a combination of the instantaneous bit error rate and a time-averaged bit error rate.

11. A tuner as claimed in any one of the preceding claims, in which the comparator is arranged to perform the comparison continuously.

12. A tuner as claimed in any one of claims 1 to 10, in which the comparator is arranged to perform the comparison periodically.

13. A tuner as claimed in any one of claims 1 to 10, in which the comparator is arranged to perform the comparison each time the tuner is powered up.

14. A tuner as claimed in any one of claims 1 to 10, in which the comparator is arranged to perform the comparison each time a change of tuned frequency is requested.

15. A tuner as claimed in any one of the preceding claims, in which the at least one stage comprises at least one frequency converter stage.

16. A tuner as claimed in claim 15, in which the at least one frequency converter stage comprises at least one mixer whose transconductance is dependant on power consumption.

17. A tuner as claimed in claim 16, in which the at least one mixer comprises at least one load whose value is adjustable to compensate for changes in the transconductance.

18.   A tuner as claimed in any one of claims 15 to 17, in which the at least one frequency converter stage comprises at least one low noise amplifier whose gain is dependent on power consumption.

19.   A tuner as claimed in any one of claims 15 to 18, in which the at least one frequency converter stage comprises at least one local oscillator whose output level is controllable by the control circuit.

20.   A tuner as claimed in any one of the preceding claims, in which the at least one stage comprises at least one intermediate frequency amplifier.

21.   A tuner as claimed in claim 20, in which the at least one intermediate frequency amplifier has a gain which is controllable by the control circuit.
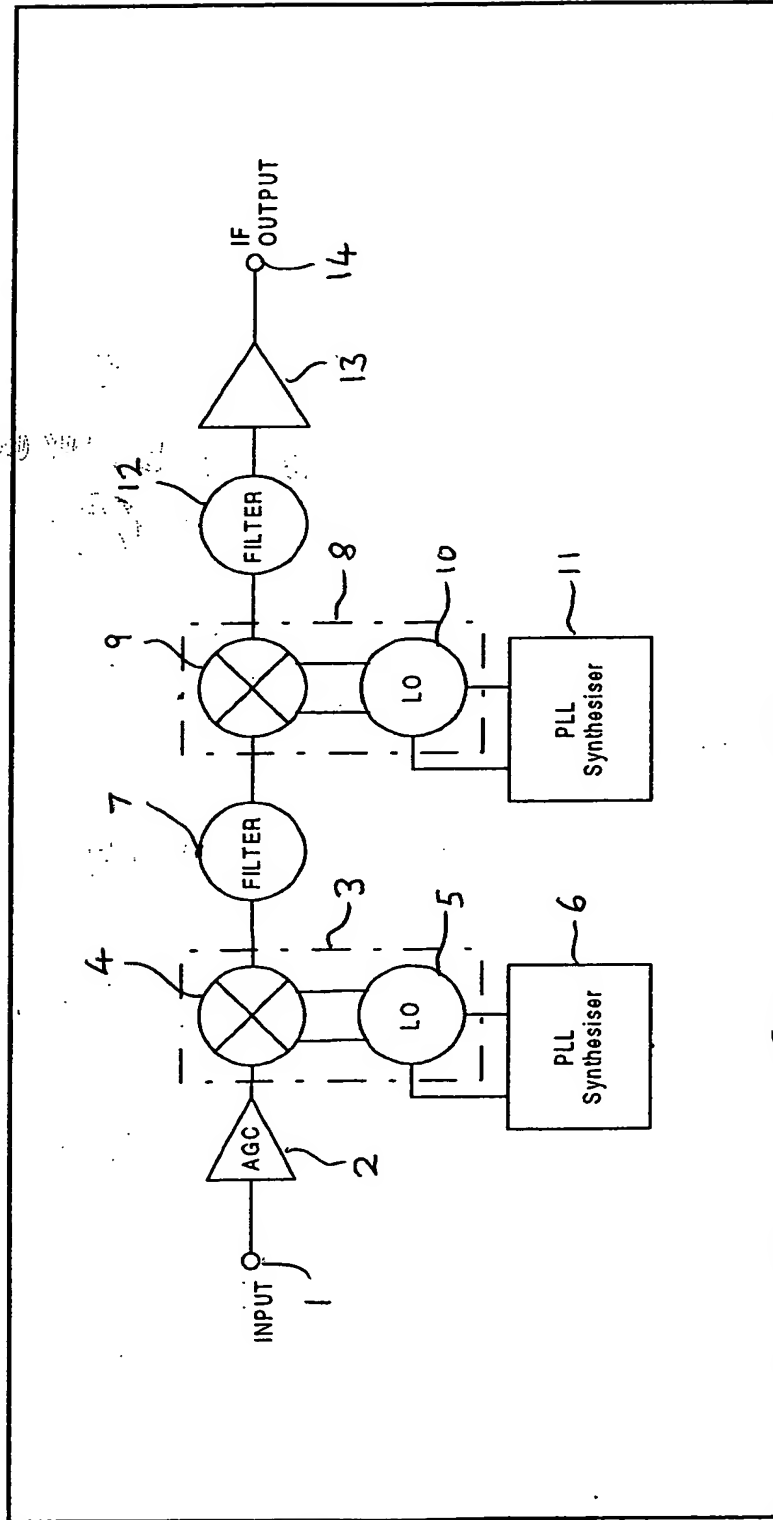
22.   A tuner as claimed in any one of the preceding claims, comprising a cable tuner.

ABSTRACT

Radio Frequency Tuner

A radio frequency tuner is provided for selecting digitally encoded channels from a cable distribution network or other reception system. The tuner has one or more stages (3, 8, 13) whose performance, such as signal to noise plus intermodulation, reduces as the stage power consumption is reduced. A comparator (35) compares the tuner performance, such as bit error rate (34), with a predetermined performance. When the tuner performance exceeds the predetermined performance, a power consumption control circuit (34) reduces the power consumption of one or more of the stages (3, 8, 13) so as to reduce the tuner power consumption while maintaining acceptable tuner performance.

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Fig 1

INPUT 1

AGC 2

4

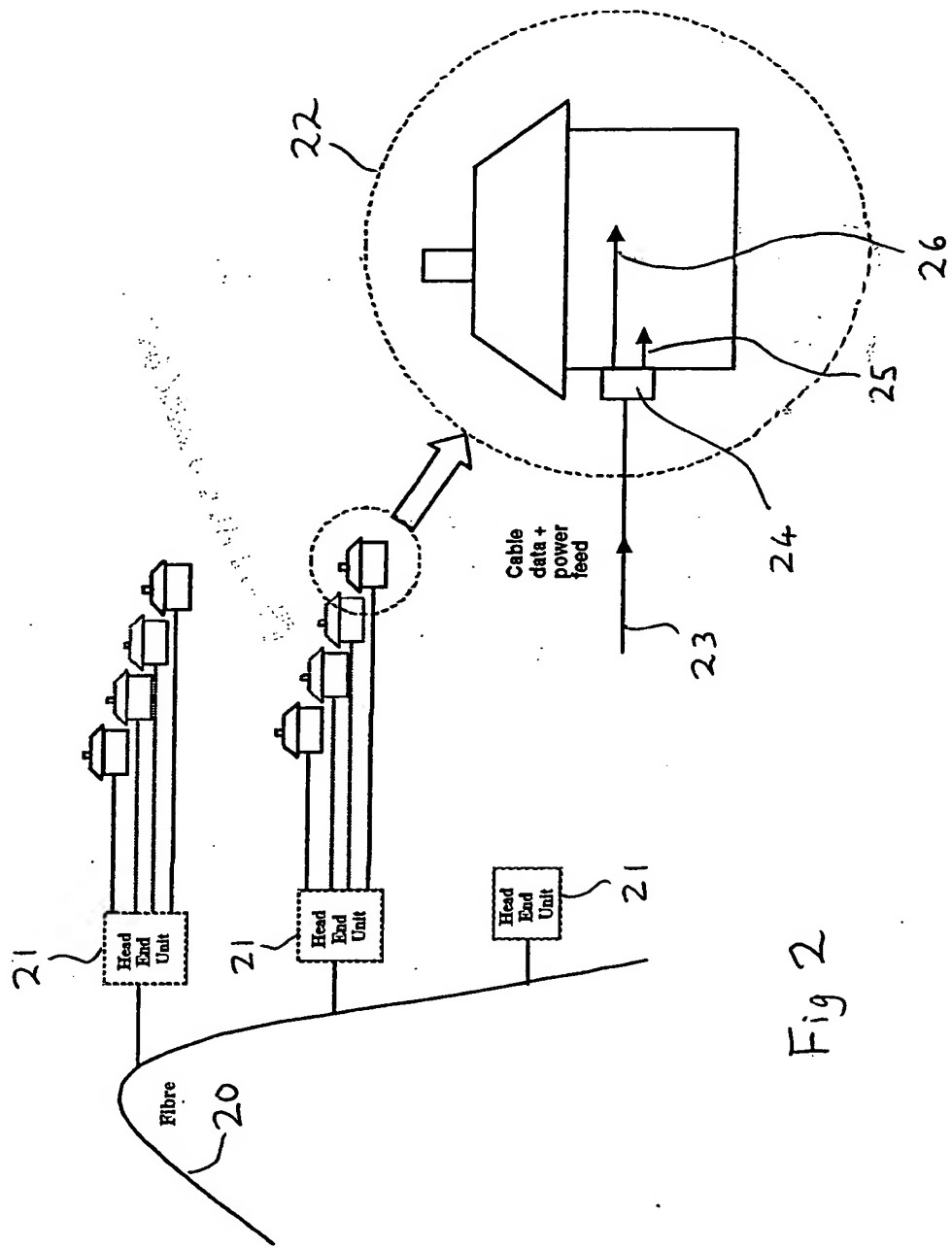3

LO 5

PLL Synthesiser 6

FILTER 7

8

9

LO 10

PLL Synthesiser 11

FILTER 12

13

IF OUTPUT 14

Head End Unit 21

Head End Unit 21

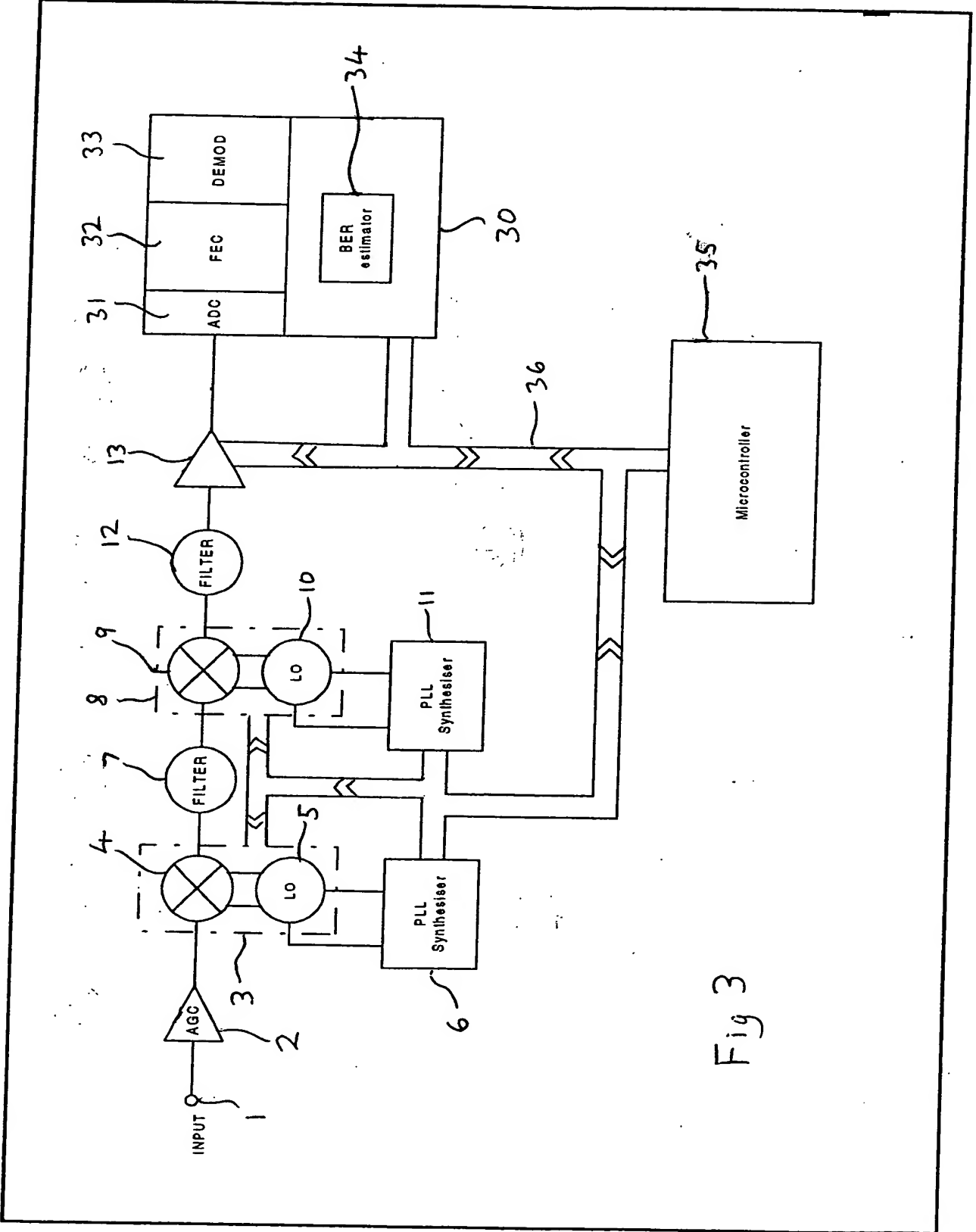Head End Unit 21
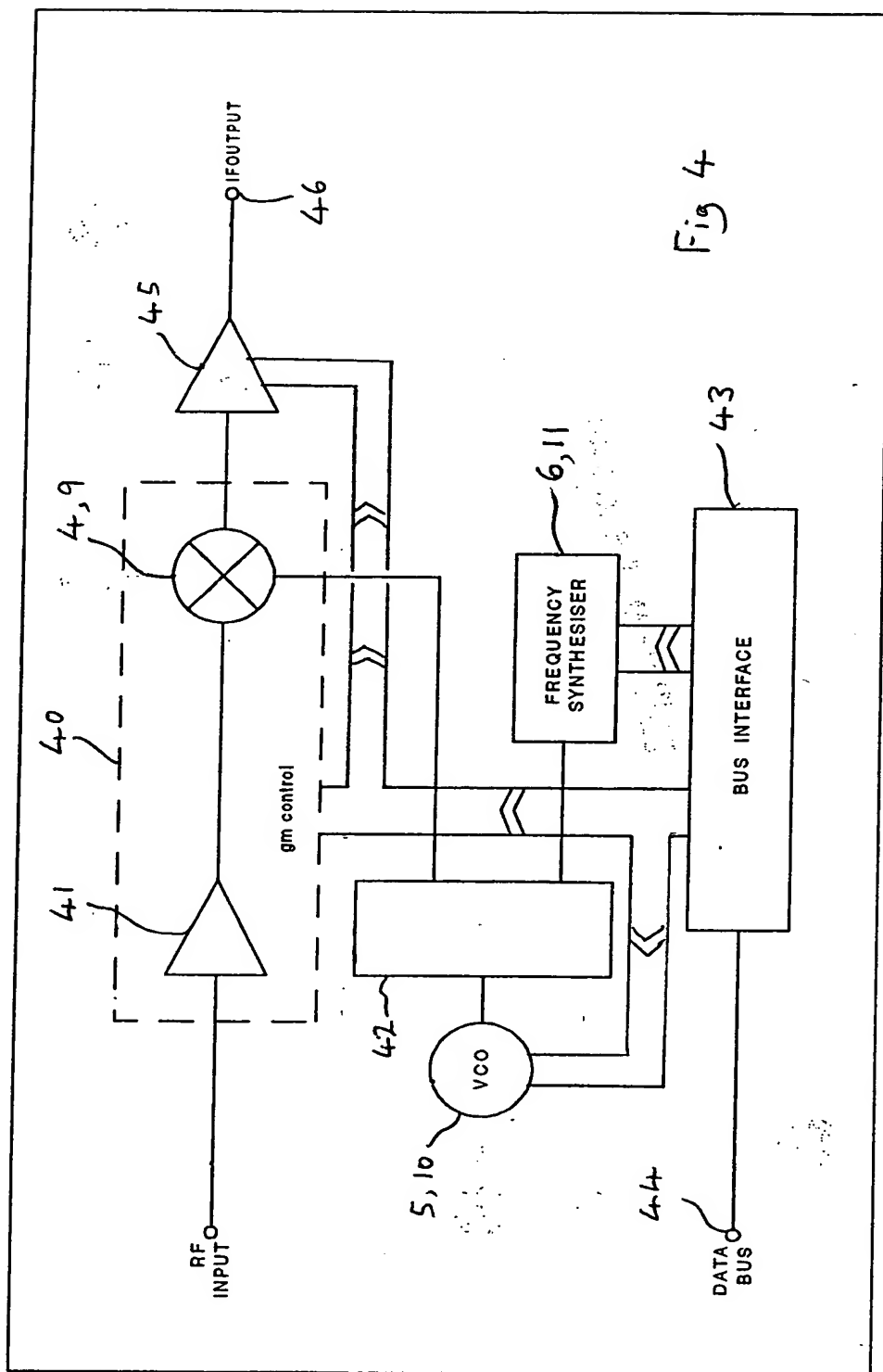
Fibre 20

Cable data + power feed

23

22

24

25

26

Fig 2

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Fig 3

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RF
INPUT ○

41

40

gm control

42

5, 10 VCO

4, 9 ⊗

45

○ IF OUTPUT
46

6, 11

FREQUENCY
SYNTHESISER

43

BUS INTERFACE

44
DATA
BUS ○

Fig 4